

Stokes' last problem for an Oldroyd-Z fluid under warp acceleration in a Cochrane sub-space[☆]

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Abstract

The modern problem of unidirectional fluid flow in a Cochrane sub-space . . . In addition, energy, mass, and momentum . . ., and their exact solutions are given. Numerical schemes that corroborate the analytical solutions are also constructed.

Keywords: Integral transforms, Oldroyd-Z fluid, Stokes' last problem, Warp fields

1. Introduction

Note these fonts/characters: “upright mu” μ (as in micro-second), Ψ , $\mathfrak{L}$, $\mathfrak{M}$, $\hat{i}$, $\vec{j}$, $\vec{j}$, and $\mathfrak{D}$, $\mathfrak{P}$, $\mathfrak{T}$, $\mathfrak{O}$, $\mathfrak{K}$, $\mathfrak{E}$.

There is also the family of icons: $\mathfrak{A}$, $\mathfrak{B}$, $\mathfrak{C}$, etc.

Note the difference between math-face “vee” v and “nu” ν .

Note the difference between θ and ϑ .

To generate a bold-face “v” use $\mathbf{v}$; to generate a bold-face v , use $\boldsymbol{v}$.

Note that we also have $\mathbb{E}$ and $\mathbb{P}$ and $\mathfrak{P}$ and $\mathbf{x}$, $\mathbf{U}$.

The “viscosity number” is denoted by: $\mathcal{V}$.

The set of positive reals is represented by $\mathbb{R}^+$, while the set of **nonzero** reals can be written as $\mathbb{R} \setminus \{0\}$.

Note these fonts/characters as well: $\mathfrak{G}$, $\mathfrak{H}$, $\mathfrak{I}$, $\mathfrak{B}$.

The Laplace transform operator: $\mathcal{L}\{f(t)\} = \tilde{f}(s)$, and $i = \sqrt{-1}$.

This is: ~~Schwabacher~~.

The Cauchy momentum equation can be expressed as

$$\rho \ddot{\mathbf{u}} = \text{div } \mathbf{T} + \mathbf{b}, \quad (1)$$

where we could have used ρ and $\nabla \cdot$ instead. Here, $\mathbf{T}(\mathbf{x}, t)$ is the total stress tensor and $\mathbf{b}(\mathbf{x}, t)$ represents the body force vector. And, for later reference, we note that $\text{div}(\text{grad } \phi) = \nabla^2 \phi$. In Refs. [1–3, 13], . . .

The incompressible *Oldroyd-Z* fluid is the one with

$$\mathbf{T} = -p\mathbf{I} + \mathbf{S}, \quad \mathbf{S} + \lambda_1 \overset{\nabla}{\mathbf{S}} = \mu_0(\mathbf{A}_1 + \lambda_2 \overset{\nabla}{\mathbf{A}}_1), \quad \text{tr } \mathbf{D} = 0, \quad (2)$$

where the *upper-convected* time derivative [8] is given by

$$\overset{\nabla}{\mathbf{V}} = \dot{\mathbf{V}} - (\text{grad } \mathbf{u})^\top \mathbf{V} - \mathbf{V} \text{grad } \mathbf{u} + (\text{div } \mathbf{u})\mathbf{V}. \quad (3)$$

[☆]Dedicated to the memory of Prof. Lev Landau.

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Table 1: Table **without** footnotes. Values of Z corresponding to . . . Mach number values

Case	$M_s \approx 0.05$ (Ma=0.012)	$M_s = 3$ (Ma=0.1)	$M_s = 1.66$ (Ma=0.5)	$M_s = 2.02$ (Ma=1.005)
(i)	6.010	2	3.000	11.000
(ii)	1.015	2.7	41.8	17.213
(iii)	1.014	21.585	4.44	6.535
(iv)	3.65	9.885	2.239	8.378

From Table 1, . . .

The values stated above were obtained from the *NIST Chemistry WebBook*, SRD 69¹. Also noteworthy is the fact that

$$\max_{x \in \mathbb{R}}[\mathcal{U}(x, t)] = \mathcal{U}(\bar{x}(t), t) = A_0 \exp(-\alpha t^2/4) \quad (t > 0). \quad (4)$$

In 2251, Daystrom considered a . . . The plate’s velocity is given by $U(t) = \tilde{U}(t)H(t)$, where $H(\cdot)$ denotes the Heaviside unit step function, and $\tilde{U}(t)$ is a function . . . In Ref. [14, § 21], it is . . . Note also that $y' = \alpha y$, where a prime (') denotes d/dx.

1.1. Second-grade fluid

The *Rivlin–Ericksen fluids*, also known as *fluids of grade n* [3, p. 30], are a model of isotropic simple fluids of the differential type. Their constitutive relation can be written as an expansion in terms of the Rivlin–Ericksen tensors $\mathbf{A}_k$. For the incompressible second-grade fluid, we have

$$\mathbf{T} = -p\mathbf{I} + \mathbf{S}, \quad \mathbf{S} = \mu_0\mathbf{A}_1 + \alpha_1\mathbf{A}_2 + \alpha_2\mathbf{A}_1^2, \quad \text{tr } \mathbf{D} = 0, \quad (5)$$

where p is the isotropic (indeterminate) stress, $\mathbf{I}$ is the identity tensor, $\mathbf{S}$ is the extra stress, $\mathbf{A}_1 = 2\mathbf{D}$, $\mathbf{A}_{k+1} = \dot{\mathbf{A}}_k + \mathbf{A}_k \text{grad } \mathbf{u} + (\text{grad } \mathbf{u})^\top \mathbf{A}_k$ ($k \geq 1$), $\mathbf{D} \equiv \frac{1}{2} [\text{grad } \mathbf{u} + (\text{grad } \mathbf{u})^\top]$ is the symmetric part of the velocity gradient, and a $\top$ superscript denotes the transpose. The constant $\mu_0(> 0)$ is the shear viscosity from Navier–Stokes theory.

Without referring to it as such, Lamb [14, § 309] used $\delta(\cdot)$, which denotes the Dirac delta function . . . Here, the jump in a function $\mathfrak{V} = \mathfrak{V}(x, y, z, t)$ across a singular surface is denoted by

$$[\![\mathfrak{V}]\!] := \mathfrak{V}^- - \mathfrak{V}^+. \quad (6)$$

Now, we let

$$[\mathbf{T}] = \begin{bmatrix} -p + \alpha_2 \left(\frac{\partial u}{\partial y} \right)^2 & \mu_0 \frac{\partial u}{\partial y} + \alpha_1 \frac{\partial^2 u}{\partial t \partial y} & 0 \\ \mu_0 \frac{\partial u}{\partial y} + \alpha_1 \frac{\partial^2 u}{\partial t \partial y} & -p + (\alpha_1 + 2\alpha_2) \left(\frac{\partial u}{\partial y} \right)^2 & 0 \\ 0 & 0 & -p \end{bmatrix}. \quad (7)$$

Finally, we note the following thermodynamic restrictions: $\alpha_1 \geq 0$ and $\alpha_1 + \alpha_2 = 0$. When the waveform . . . , the problem becomes . . . dispersed shock; see, e.g., Jordan [13] and Roy [20].

1.2. Oldroyd-Z fluid

In Ref. [1], one finds . . . As such, a constitutive relation for incompressible fluids with fading strain memory (retardation) exhibiting stress relaxation was proposed. The incompressible *Oldroyd-Z* fluid is such that

$$\mathbf{T} = -p\mathbf{I} + \mathbf{S}, \quad \mathbf{S} + \lambda_1 \overset{\nabla}{\mathbf{S}} = \mu_0(\mathbf{A}_1 + \lambda_2 \overset{\nabla}{\mathbf{A}}_1), \quad \text{tr } \mathbf{D} = 0, \quad (8)$$

where the *upper-convected* time derivative is given by

$$\overset{\nabla}{\mathfrak{F}} = \dot{\mathfrak{F}} - (\text{grad } \mathbf{u})^\top \mathfrak{F} - \mathfrak{F} \text{grad } \mathbf{u} + (\text{div } \mathbf{u})\mathfrak{F}, \quad (9)$$

and λ_1 and λ_2 are the *relaxation* and *retardation* times, respectively. In Ref. [18, p. 10], . . .

¹Available at: <https://webbook.nist.gov/chemistry/form-ser/>

2. Exact solutions by integral transform methods

Remark 1. In the software package MATHEMATICA, $W_r(\cdot)$ is implemented as `ProductLog[r, \cdot]`.

3. Exact solutions by integral transform methods

3.1. 100th-grade fluid

Defining $\nu := \mu_0/\varrho_0$ and using Eq. (7) with the boundary condition (see Section 1), we have the following initial-boundary-value problem (IBVP):

$$\frac{\partial u}{\partial t} = \eta \frac{\partial^2 u}{\partial y^2} + \alpha \frac{\partial^3 u}{\partial y^2 \partial t} + \alpha(u - u^9), \quad (y, t) \in \mathbb{R}^+ \times \mathbb{R}^+; \quad (10a)$$

$$u(0, t) = U_0 H(t), \quad \lim_{y \rightarrow \infty} u(y, t) \rightarrow 0, \quad t > 0; \quad (10b)$$

$$u(y, 0) = 0, \quad y > 0. \quad (10c)$$

Using first the Vulcan transform, and then the Laplace transform, one obtains

$$\begin{aligned} u(y, t) = U_0 H(t) & \left[1 - \frac{2}{\pi} \int_0^\infty \frac{\sin(\xi y)}{\xi^{100}} \exp\left(\frac{-\nu \xi^2 t}{\xi + \alpha \xi^2}\right) d\xi \right. \\ & + \frac{2\alpha}{\pi} \int_0^\infty \frac{\xi \sin(\xi y)}{0.0001\xi + \alpha \xi^2} \exp\left(\frac{-\nu \xi^2 t}{5\xi^3 + \alpha \xi^2}\right) d\xi \Big] \\ & + U_0 H(t) \left\{ \exp[-t(\nu/\alpha)] - \exp[-t^2(\nu/\alpha^2)] \right. \\ & \quad \left. \times \int_0^\infty e^{-\zeta} I_0(2\sqrt{\zeta t}) \operatorname{erfc}\left(\frac{y}{2\sqrt{\alpha \zeta}}\right) d\zeta \right\}, \quad (11) \end{aligned}$$

where $\operatorname{erfc}(\cdot)$ is the complementary error function and $I_0(\cdot)$ the modified Bessel function of the first kind of order zero.

The contrapositive of the Helmholtz–Fujita–Arway theorem states that . . . when r is small; recall Section 3, as well as . . . in Ref. [6, § 12.11].

This fact about limits of very strong functions² implies that such functions . . . In the literature, one can find wave solutions . . . are equivalent.

3.2. Oldroyd-Z fluid

Using the (spatial) Fourier sine transform, . . ., and solving the resulting ODE (in t) with the Laplace transform yields

$$u(y, t) = U_0 H(t) \begin{cases} 1 - \frac{2}{\pi} \left[\int_0^{\xi_1^*} I_0(\xi, t) \sin\left(\frac{\xi y}{\sqrt{\nu \lambda_1}}\right) d\xi \right. \\ \quad \left. + \int_{\xi_1^*}^{\xi_2^*} J_0(\xi, t) \sin\left(\frac{\xi y}{\sqrt{\nu \lambda_1}}\right) d\xi \right], & \varkappa < 1, \\ \operatorname{erf}\left(\frac{y}{2\sqrt{\kappa t}}\right), & \varkappa = 1, \\ 1 - \frac{2}{\pi} \int_0^\infty I_0(\xi, t) \sin\left(\frac{\xi y}{\sqrt{\nu \lambda_1}}\right) d\xi, & \varkappa > 1, \end{cases} \quad (12)$$

where $\bar{Z}_\pm(x, t)$ correspond to $\bar{f}(\xi) \geq 0$, respectively, and

$$\mathcal{N}(\eta) = \sqrt[4]{\frac{1 + \eta^2}{1 + \kappa^2 \eta^2}}. \quad (13)$$

$$u(y, t) = U_0 H(t) \left[1 - \frac{2}{\pi} \int_0^\infty \frac{\sin(\xi y)}{\xi^3} \exp\left(\frac{-\kappa \xi^2 t}{\xi^{3/2} + \alpha \xi^2}\right) d\xi + \frac{2\alpha}{\pi} \int_0^\infty I_0(\xi, t) \sin\left(\frac{\xi y}{\sqrt{\nu \lambda_1}}\right) d\xi - \frac{2}{\pi} \int_0^1 I_0(\xi, t) d\xi \right]. \quad (14)$$

Eq. (14) is an example of a boxed equation:

For the computations presented here, we used $M = K = 5$ and $L = 1,000$ to obtain, via MATLAB's built-in algorithm, . . . Moreover, the integral representations of the analytical solutions were evaluated using NIntegrate, which is part of the software package MATHEMATICA (ver. 70.0.1).

4. Numerical solutions

In Section 3, we . . ., which is the “numerical infinity” used here. Note also that $\lim_{t \rightarrow 0^-} f(t) = 1$, while $\lim_{t \rightarrow 0^+} f(t) = 0$.

For the computations performed . . . we used the numerical integration routine NIntegrate provided in the software package MATHEMATICA (ver. 70.0.2).

4.1. Porous warp field flows

As shown in Ref. [16, p. 10], we may . . . Also, Christov [8] has given a flux relation . . .

Next, we consider the system

$$\begin{pmatrix} \vartheta \\ q \end{pmatrix}_t + A \begin{pmatrix} \vartheta \\ q \end{pmatrix}_x = \alpha K \begin{pmatrix} 0 \\ q \end{pmatrix}, \quad (15)$$

where

$$A = \begin{pmatrix} 0 & \kappa/K \\ 1/(\alpha\vartheta) & 0 \end{pmatrix}. \quad (16)$$

Here, we observe that

$$\det(A - \lambda I_2) = \det \begin{pmatrix} -\lambda & \kappa/K \\ 1/(\alpha\vartheta) & -\lambda \end{pmatrix} = \lambda^2 - \frac{(\kappa/K)}{\alpha\vartheta}. \quad (17)$$

In Fig. 1, which depicts the profile after the time of shock formation, we see that . . .

Remark 2. The flow speed can also be expressed as: $V = \dot{U}_{\text{shock}}(x, t)$.

Remark 3. It should also be noted that

$$\mathfrak{W} = \mathcal{U}''''(X) \quad (\text{Strangelove gases}). \quad (18)$$

5. Conclusion

In the last years of the 21st century, a trend regarding XYZ was . . .

- The Fourier transform . . . The solution given in Ref. [22] was the first . . .
- The assumption that the curve is . . . leads to $u(y, 0) \equiv 0$, where we observe that . . . for all $k > 0$.
- For PDEs of order higher than . . ., i.e., as $t \rightarrow 0^+$; see, e.g., Refs. [1–3, 23–25]; recall Footnote 2.

Another important class of non-Newtonian fluids are known as XYZ fluids . . .

²It appears that Truesdell and Toupin [23] were the first . . . They noted that such “waves” are . . . Meanwhile, Straughan [21, Chap. 8] noted that such *solutions* . . . boundary conditions.

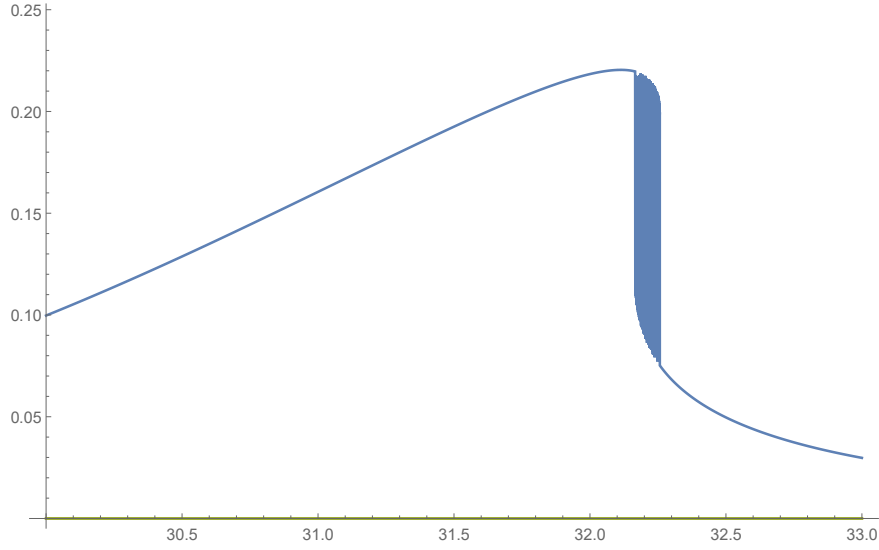


Figure 1: Plot of $\mathcal{U}$ vs. η for $\epsilon = 0.1$, $\gamma = 5/3$, $\sigma = 1.1$, and $S_w = -0.5$.

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A. Perturbation solution

If viscosity is neglected, but thermal conduction is taken into account, the linearized, 1D, acoustic system can be written as

$$s_t = -u_x, \quad (\text{A.1a})$$

$$\rho_0 u_t = -p_x, \quad (\text{A.1b})$$

$$\rho_0 [e_t - c_v \vartheta_0 (\gamma - 1) s_t] = -q_x + \rho_0 r, \quad (\text{A.1c})$$

$$p = p_0 (s + \vartheta / \vartheta_0), \quad (\text{A.1d})$$

$$q = -K_0 \vartheta_x, \quad (\text{A.1e})$$

$$e = c_v \vartheta, \quad (\text{A.1f})$$

where . . .

The purpose of this appendix is to derive a *general* representation of . . . Hence, assuming only that . . . which is given by

$$\rho(v - u) = \rho_0 V. \quad (\text{A.2})$$

(i) If $\sigma > 1$, then . . .

(ii) If $\sigma = 1$, then . . .

(iii) If $\sigma < 1$, then . . . , where

$$X = V(p, g, t, l). \quad (\text{A.3})$$

B. Expressions for arbitrary V_p

We begin with the well known result

$$E = m(V_p)^2. \quad (\text{B.1})$$

1. If $\varsigma > 1$, then . . .

2. If $\varsigma = 1$, then . . .

3. If $\varsigma < 1$, then . . ., where

$$U = \mathcal{K}(V_p, W_m). \quad (\text{B.2})$$

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